

# C101-D9S

## Application board (rev. C) User guide



### Abstract

This document explains the use of C101-D9S application board. The C101-D9S board enables customers to evaluate L-band GNSS correction services with the NEO-D9S correction data receiver.



## Document information

<b>Title</b>	<b>C101-D9S</b>	
Subtitle	Application board (rev. C)	
Document type	User guide	
Document number	UBX-20031865	
Revision and date	R03	17-Jan-2022
Disclosure restriction	C1-Public	

This document applies to the following products:

<b>Product name</b>	<b>Type number</b>	<b>Firmware version</b>	<b>PCN reference</b>
C101-D9S	C101-D9S-0-00	PMP 1.04	N/A

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# 1 Introduction

The C101-D9S board is a convenient tool that allows customers to become familiar with the u-blox NEO-D9S L-band correction data receiver. The board provides facilities for evaluating the product and demonstrating its key features.

NEO-D9S is a satellite data receiver for L-band correction broadcasts and can be configured for use with a variety of correction services. Using such correction services enables high precision navigation globally in multiple regions, as well as coverage across continents.

The C101-D9S application board offers:

- NEO-D9S module for use as L-band correction data receiver
- USB connection for communication and power supply
- L-band antenna connection for receiving the satellite data stream
- Arduino shield connection

## 1.1 Package contents

The delivered package contains:

- C101-D9S board
- L-band antenna
- Antenna ground plane (12 cm circular)
- USB interconnect cable
- Jumper connectors

Prior to using the board, it is useful to download the appropriate evaluation software and keep handy the documents listed in the Related documents section.

## 2 C101-D9S product overview

### 2.1 Components

C101-D9S houses the NEO-D9S L-band correction data receiver. The board is powered from the USB cable connection or via Arduino shield. The main components of the board are listed below and shown in Figure 1 and Figure 2:

- Native USB port
- FTDI USB bridge
- SMA RF connector and antenna supply capability (L-band)
- UART2 interface through Arduino shield
- NEO-D9S RESET button
- NEO-D9S SAFEBOOT button

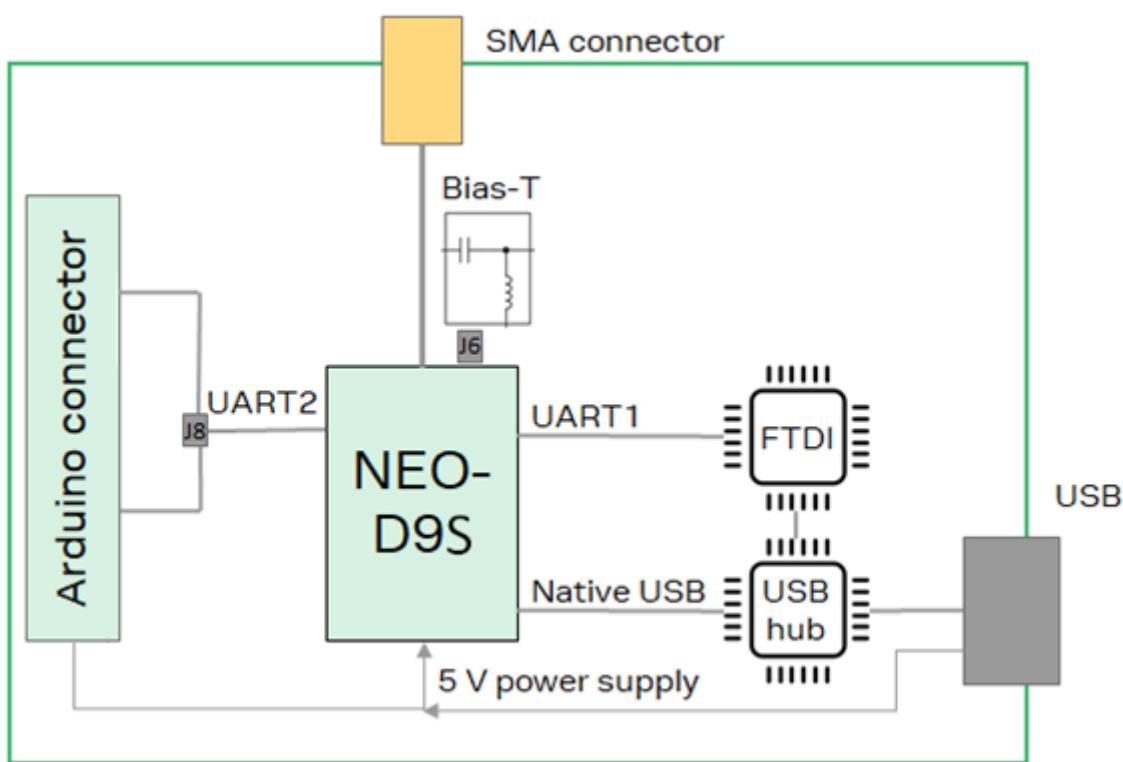


Figure 1: C101-D9S block diagram

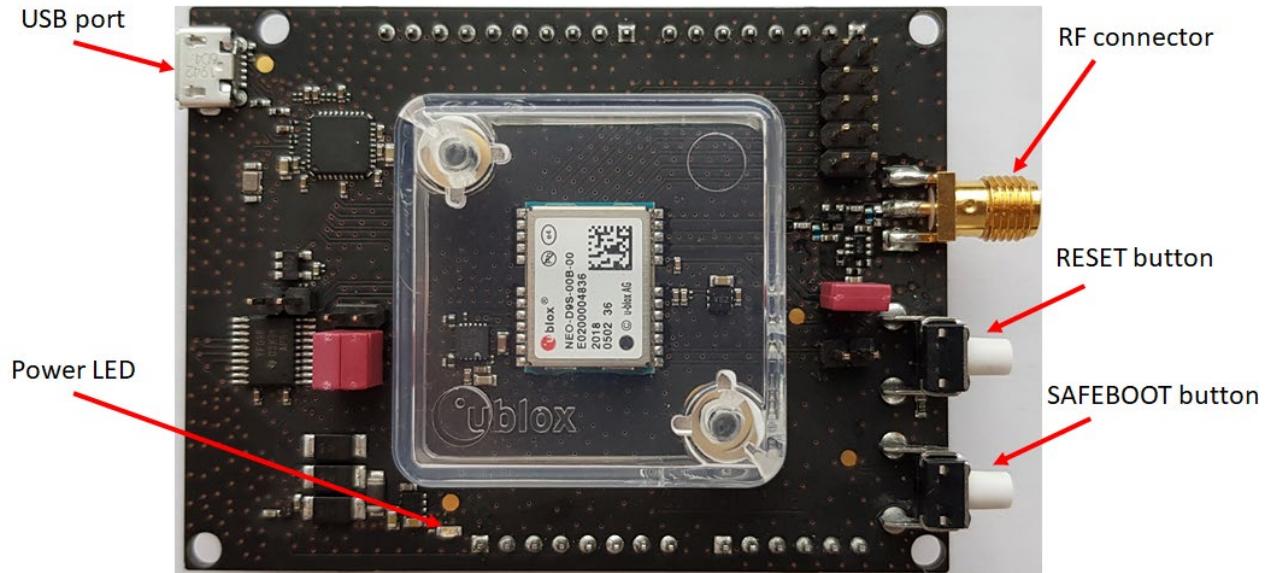


Figure 2: C101-D9S quick start basic overview

## 2.2 Jumpers

The board is delivered with the following default jumpers:

- **J6:** This jumper provides 3.3 V power supply to an external active antenna plugged to the SMA RF connector. The current limit circuit is also enabled up to 60 mA.
- **J8:** This jumper switches the communication from the UART2 of the NEO-D9S to the J2 or J3 connector of the Arduino shield (refer to Appendix D for further details).

Figure 3: C101-D9S jumpers overview

For further details, see the C101-D9S schematic in Appendix D.

### 3 C101-D9S standalone operation

This section provides some quicksteps to enable NEO-D9S standalone operation, and connecting via u-center (see u-center user guide [3]).

- Connect the supplied L-band antenna to the RF SMA connector. Ensure good visibility of the GEO communication satellites.
- Connect the USB to a Windows PC, this will power the board. The FTDI and USB drivers will be installed automatically from Windows Update when the user connects the board for the first time.
- The power LED will turn on in blue.
- Start the Device Manager utility from Windows. Two new ports will be visible under the Ports tab: the USB Serial Device is the Native USB port and the USB Serial Port is the FTDI USB bridge port, as shown in Figure 4.



Figure 4: Windows Device Manager Ports identifications

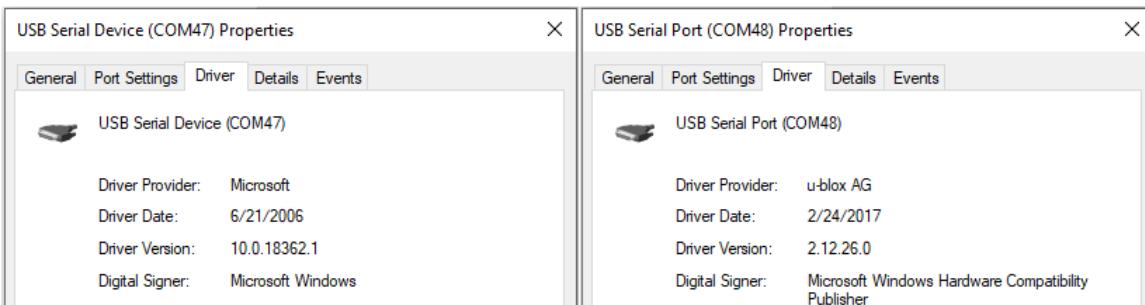


Figure 5: FTDI USB bridge and USB ports properties

- Start u-center and connect to one of the COM ports. If you are using the FTDI USB bridge, make sure the baud rate in u-center is set to 9600.
- Poll UBX-MON-VER message and check the content as shown in Figure 6.

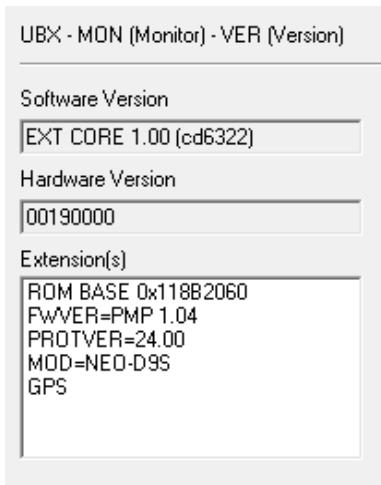


Figure 6: UBX-MON-VER message

NEO-D9S needs to be properly configured to receive the L-band signal correction data. See Appendix B for the default NEO-D9S L-band configuration, which can be adapted for other services.

The messages UBX-MON-PMP and UBX-RXM-PMP (see Figure 7 and Figure 8) can be polled or enabled to check respectively the reception of the signal and the decoded correction data.

UBX - MON (Monitor) - PMP (Point-To-Multipoint)						
locked	frameSync	timeTag	lockTime	centerFrequency	cno	cnoFrac
●	1	6150000	2065000	1545490434	45	0.09

Figure 7: UBX-MON-PMP message

UBX - RXM (Receiver Manager) - PMP (Point to Multipoint)	
Version:	1
TimeTag [ms]:	6084507
UniqueWord[0]:	0xE15AE893
UniqueWord[1]:	0xE15AE893
UniqueWordBitErrors:	0
FEC bits:	1
Eb/N0 [dB]:	11.500
ServiceID:	0xC685
SpareByte:	0x7F
UserData bytes:	504
UserData:	
	0x7E 64 6D 4C 9A A7 2C 70 79 3A 04 1F 64 7B A4 E1 C6 BB 19 7B 0x76 19 FA 24 72 C0 B2 D1 06 2C BA 90 40 09 5D F9 56 60 5C 74 0xB2 EA C4 D6 2E 93 EA E1 41 C2 1A 65 EB FC 04 2E 3A C4 93 94 0xFA 3F D1 B8 EE 5A 02 B6 9B D9 5B A7 7C DD 8C 2C CE 68 52 C1 0xE5 89 EA 7D 40 0E E7 6F 3B 13 7D 89 62 35 5D C1 5F B1 C4 8E 0xDB E8 80 03 C0 F3 20 39 D6 D0 7C F4 94 4A 72 F9 DC C6 E6 23 0xAE 96 F3 F1 BA FF 50 CF 98 30 53 50 64 36 62 7B FB 6A 79 A4 0x61 B0 43 8F 06 EA 29 E2 9F 23 DC F7 25 C1 2C DA 93 AF 5F 54

Figure 8: UBX-RXM-PMP message

## 4 C101-D9S operation with C099-F9P

It is possible to use the C101-D9S board together with C099-F9P. Figure 9 shows how to interface the C101-D9S board with the C099-F9P board.

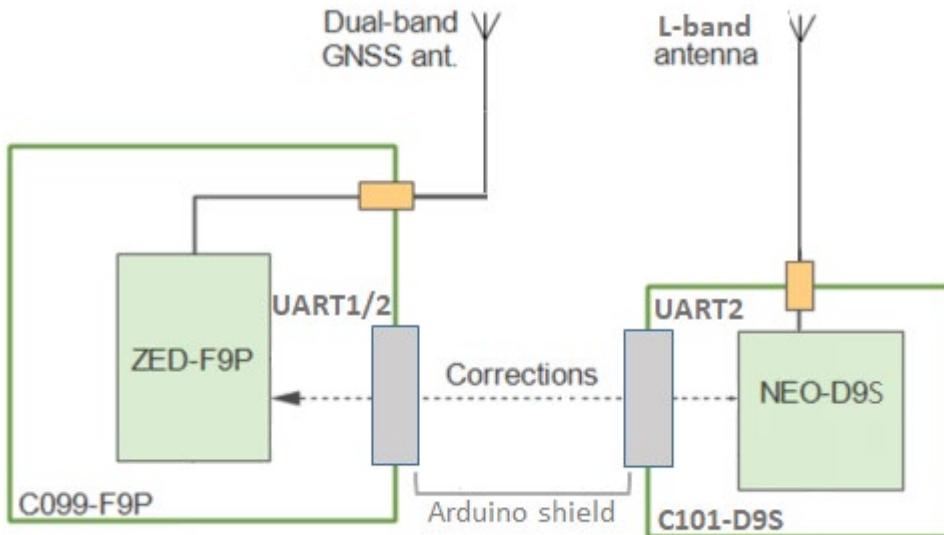


Figure 9: C101-D9S - C099-F9P interfacing scheme

Figure 10 shows the placement of the Arduino connectors on the C101-D9S board and Figure 11 shows how to physically connect the C099-F9P board to the C101-D9S board via the Arduino shield. Jumper J18 on the C099 board is needed for the ZED-F9P to receive the correction data on the UART1 port. See the C099 application board User guide [4] for further details.

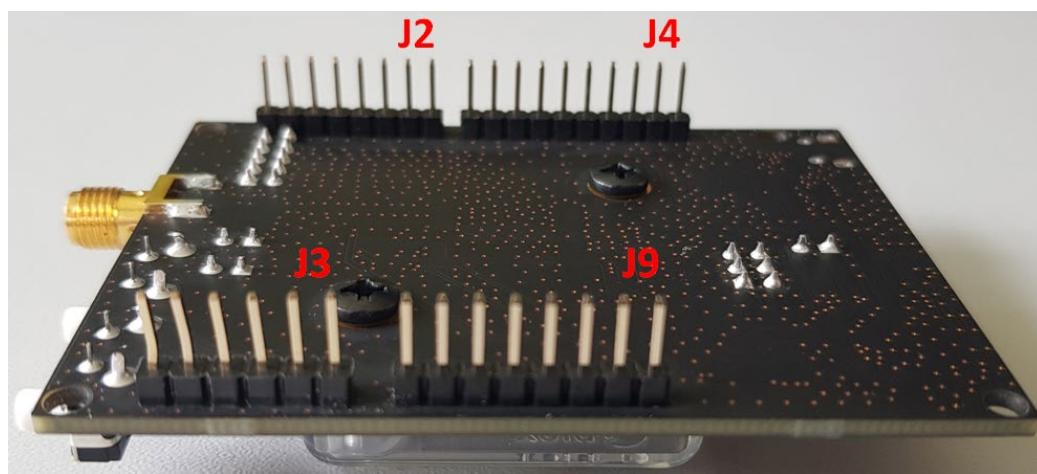


Figure 10: C101-D9S Arduino connectors

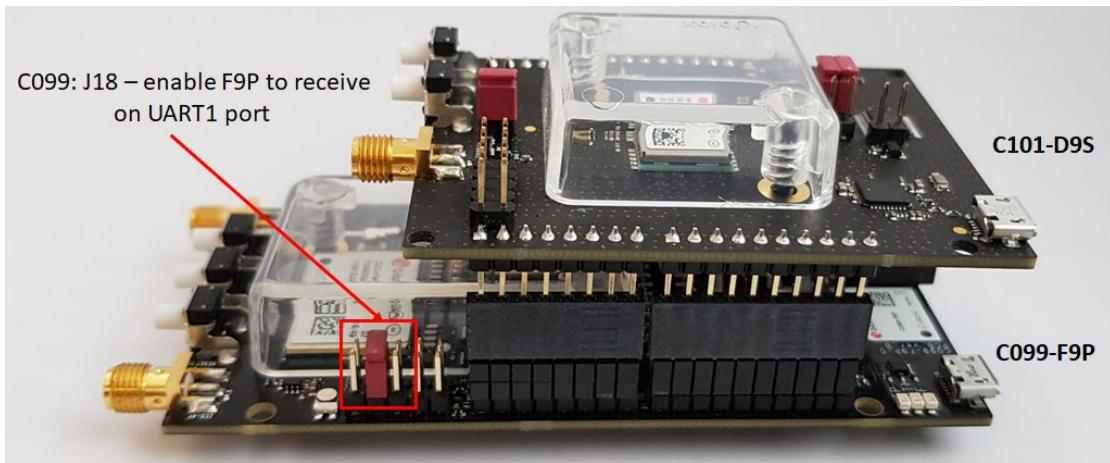
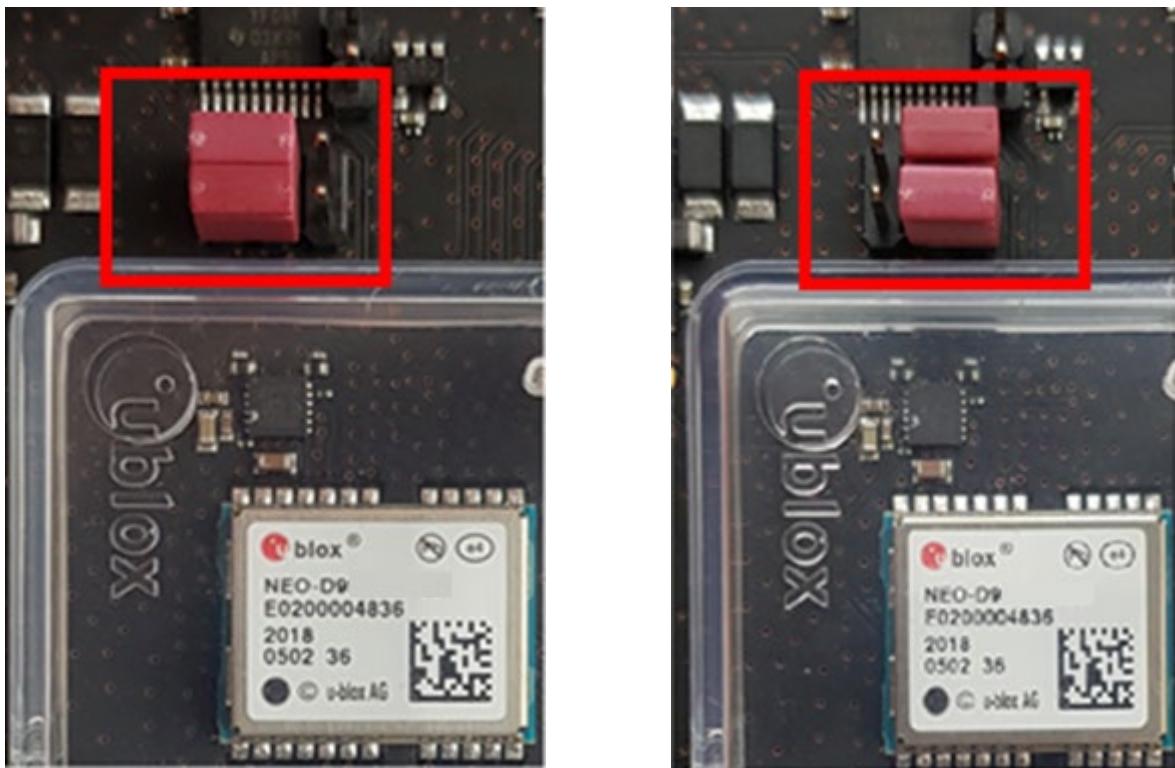


Figure 11: Connecting C101-D9S to C099-F9P

Depending on the position of jumper J8 on the C101-D9S board (as shown below) the ZED-F9P housed on the C099-F9P board will receive the correction data on the UART1 or the UART2 port:



The ZED-F9P receives the correction data on  
UART1 port.

The ZED-F9P receives the correction data on  
UART2 port.

For further details, see the C101-D9S schematic in Appendix D.

UBX protocol needs to be enabled in output on the UART2 interface of the NEO-D9S to allow the communication, using the following configuration item:

#### **CFG-UART2OUTPROT-UBX=1**

For further details regarding receiver configuration, see the related Interface description [5].

# Appendix

## A Glossary

Abbreviation	Definition
FTDI	Future Technology Device International
GEO	Geostationary Earth Orbit
LED	Light Emitting Diode
LNA	Low Noise Amplifier
RF	Radio Frequency
RHCP	Right Hand Circular Polarized
SMA	SubMiniature version A
UART	Universal Asynchronous Receiver Transmitter
USB	Universal Serial Bus

Table 1: Explanation of the abbreviations and terms used

## B NEO-D9S L-band configurations

Correction services from several providers are available via the L-band communication satellites. The service provider will have several correction service specific configurations that need to be configured before the receiver can provide the relevant service provider data such as:

- Service provider service ID
- Service provider frequency based on geographical location
- Service provider data rate

This means that the frequency allocation for a particular service provider could change. Service providers do provide information on any frequency changes when required.

The NEO-D9S default L-band configuration keys are listed below:

- CFG-PMP-CENTER\_FREQUENCY = 1539812500 Hz
- CFG-PMP-SEARCH\_WINDOW = 2200 Hz
- CFG-PMP-USE\_SERVICE\_ID = 1 (true)
- CFG-PMP-SERVICE\_ID = 50821
- CFG-PMP-DATA\_RATE = 2400 (B2400) bps
- CFG-PMP-USE\_DESCRAMBLER = 1 (true)
- CFG-PMP-DESCRAMBLER\_INIT = 23560
- CFG-PMP-USE\_PRESCRAMBLING = 0 (false)
- CFG-PMP-UNIQUE\_WORD = 16238547128276412563

The NEO-D9S correction data receiver is fully compliant with the u-blox configuration concept. The messages UBX-CFG-VALSET, UBX-CFG-VALGET and UBX-CFG-VALDEL are used to configure the above keys. See the NEO-D9S Integration manual [1] for further details.

## C L-band antenna specification

The following is an overview of the provided Inpaq L-band antenna, LBAND01D-S6-00:

### Patch

Characteristics	Specification	
Frequency Range	1525~1559 MHz	
Peak Gain	1525 MHz	3.8 dBiC
	1537.5 MHz	5.6 dBiC
	1550 MHz	3.8 dBiC
	1559 MHz	1.3 dBiC
Polarization	RHCP	
Axial Ratio	3.0 dB typ.	
VSWR	2.0 typ.	
Impedance	50 ohm	

### Filter / LNA

Characteristics	Specification		
Frequency Range	1525~1559 MHz		
Gain	1525 MHz	27.0±3.0 dB	
	1537.5 MHz	27.0±3.0 dB	
	1550 MHz	27.0±3.0 dB	
	1559 MHz	26.0±3.0 dB	
Noise Figure	2.0 dB typ.		
Filter Out Band Attenuation	F <sub>1</sub> = 1525 MHz	F <sub>1</sub> -50 MHz	> 65 dB
		F <sub>1</sub> -100 MHz	> 70 dB
	F <sub>2</sub> = 1559 MHz	F <sub>2</sub> +50 MHz	> 65 dB
		F <sub>2</sub> +100 MHz	> 75 dB
Output VSWR	2.0 typ.		
Operation Voltage	3.0~5.0 V		
Current	13.0±3.0 mA		

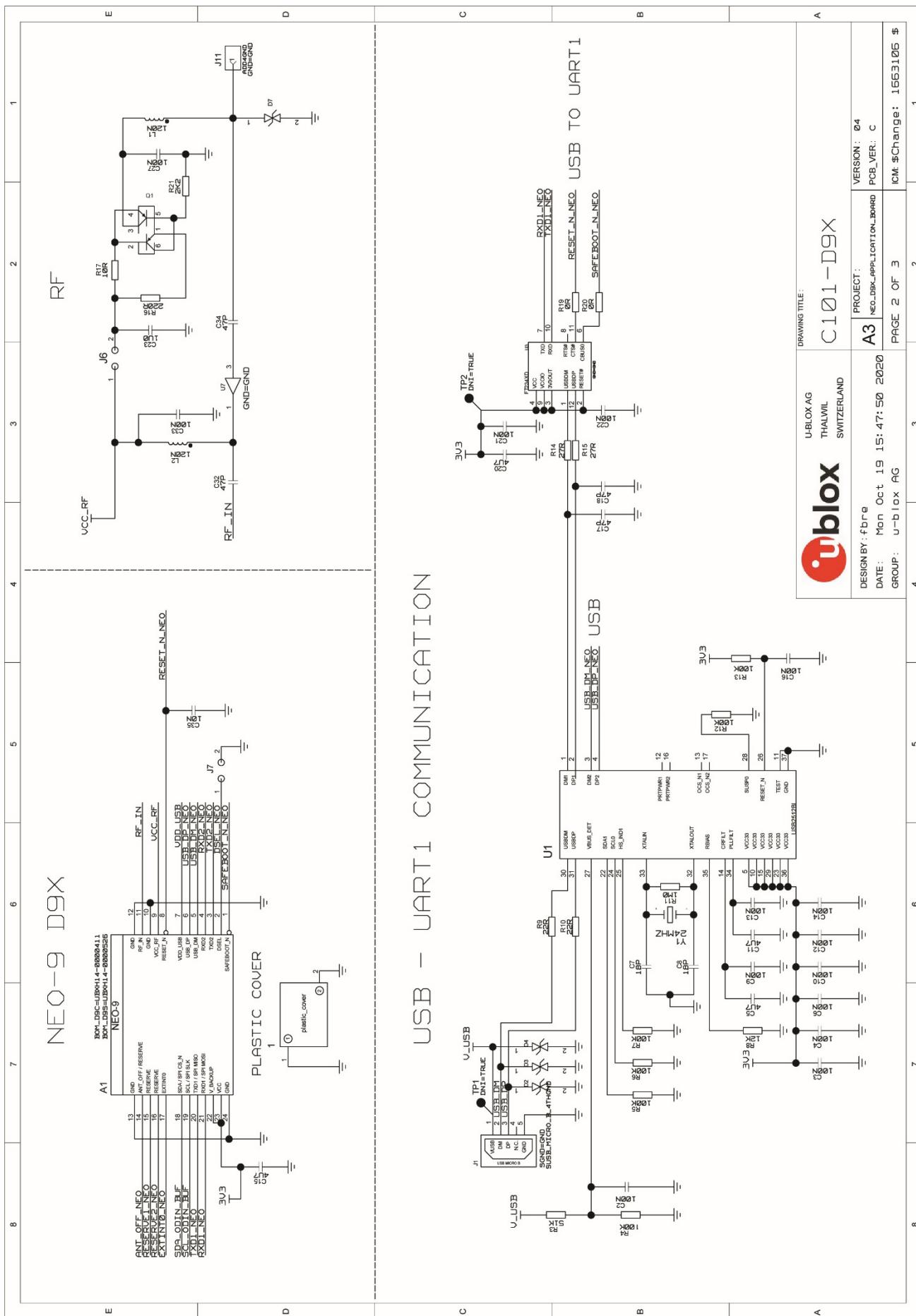
### Overall Specification (Through Antenna, LNA, Without Cable Loss)

Characteristics	Specification	
Frequency Range	1525~1550 MHz	
Gain	1525 MHz	30.8±3.0 dB
	1537.5 MHz	32.6±3.0 dB
	1550 MHz	30.8±3.0 dB
	1559 MHz	27.3±3.0 dB
'Output VSWR	2.0 typ.	
Operation Voltage	3.0~5.0 V	
Current	13.0±3.0 mA	

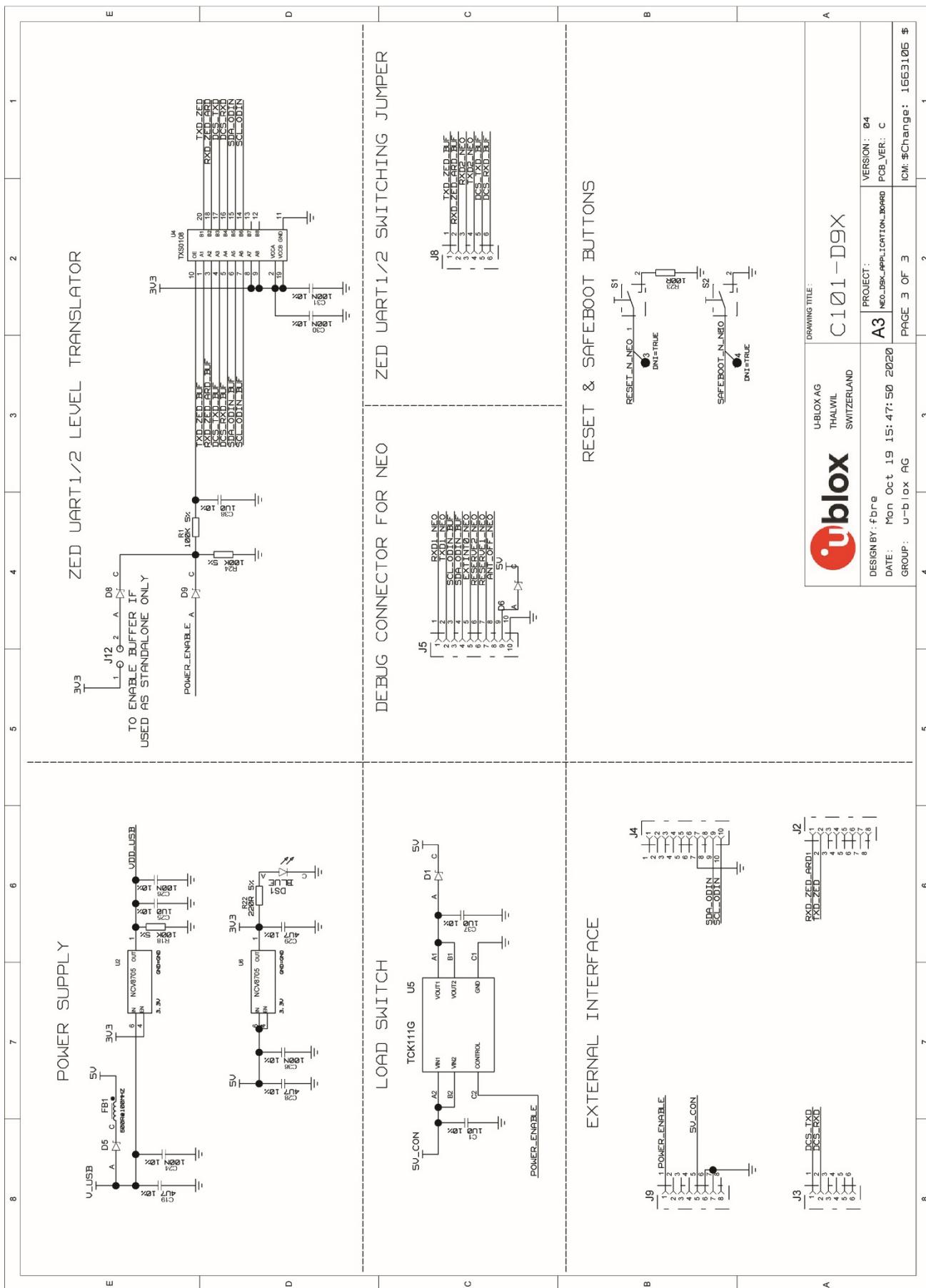
See the NEO-D9S Integration manual [1] for further details.

## D C101-D9S schematics

The following pages show the complete schematics for the C101-D9S evaluation board.



## Appendix



## Related documentation

- [1] NEO-D9S Integration manual, [UBX-19026111](#)
- [2] ZED-F9P Integration manual, [UBX-18010802](#)
- [3] u-center User guide, [UBX-13005250](#)
- [4] C099 application board User guide, [UBX- 18063024](#)
- [5] U-blox D9 PMP 1.04 Interface description, [UBX- 21040023](#)

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## Revision history

Revision	Date	Name	Comments
R01	30-Jul-2020	dama	Initial release
R02	24-Jun-2021	dama	Add chapter 4: C101-D9S operation with C099-F9P
R03	17-Jan-2022	dama	Chapter 4 update

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